## **Response to F. Parrenin (Referee)**

This manuscript present a novel method to infer paleo-accumulations from age-depth observations in an ice core. It is based on control theory. It is the first time, to my knowledge, that control theory is used for this problem. For this reason, I think this manuscript is important.

My biggest question is however: does this manuscript really belong to CP? This is really a methodological paper, the application of the method to James Ross Island is anecdotic. Therefore, I would rather see this manuscript in Geoscientific Model Development. But I leave this question up to the editor and I will continue my review.

This is also, to our knowledge, the first time that control theory is used to infer paleoaccumulation. It is not a new problem but it has been often overlooked with the assumption that paleo-acculation is related to paleo-temperatures. That relation has been proven wrong in coastal areas of Greenland and Antarctica (e.g., Kapsner et al 1995). We believe that this paper is timely as new ice-cores are been drilled in coastal areas and new datasets of along-depth ice-flow are available (e.g., Kingslake et al, 2014). This is precisely why we believe that CP is the perfect journal for this paper as we want to expose this new method to the ice-core community. We believe that the method presented in this paper is a systematic new approach to the problem that is ready for this new datasets.

A further important remark concerns the introduction of the control theory concepts in the manuscript. CP's reader will not be familiar with them so they should be carefully explained. First, in equation (3), J is a function of (a, m, A0; A). A is separated by a ";" from the other variables. It is not clear what that means. A itself is a function of (a, m, A0) so at first glance, one does not understand why A is also part of the variables.

a, m, A0 and A are not variables but functions of time or space, J is a functional. ';' is commonly used in maths to differentiate subgroups of variables or functions. In this case a, m and A0 are the control functions, what we want to extract and A can be derived from them. We have rewritten Section 2.2 to highlight that a, m, A0 and A are functions.

Second, it is not obvious at all why the optimization problem in eqs (1) and (3) is equivalent to the optimization problem in eq. (5). The reference (Tröltzsch, 2010) is cited so I imagine one can find the answer to this question in this reference. But a general qualitative explanation would be helpful here.

We have rewritten the text to make Eq 5 clearer, and we add the verification of this in the new Appendix, where we have included the mathematical details.

Third, it is not clear how one goes from eq. (5) to eqs. (6) and (7). Again, this should be more carefully explained.

We have included an appendix with the derivation of former Equations (6) and (7).

In the discussion, the authors might also want to compare their new control based method, with inverse problems based methods like the ones presented in Lemieux-Dudon et al.

(QSR, 2010) or Fudge et al. (CP, 2014, based on Waddington et al., 2003). A review of pros and cons of the different methods would be helpful.

We agree that that comparison would be interesting but that it is beyond the scope of this paper. It is not an easy task as the different methods suggested solve different equations with different datasets but certainly an inter-comparison with synthetic data would be interesting.

Also in the discussion, it would be interesting to know if this method can be extended to more realistic ice flow models. The model described here is 1D and has a steady velocity profile which is quite a strong assumption.

Good suggestion. We have rewritten the end of the discussion. We would like to add that even when the flow models we use in the paper are simple approximations, they are not steady as they vary with time as a function of the surface accumulation.

Concerning the applications of the method, I think they are not very well chosen. Indeed, in both applications, melting is zero and in this case, there is no need of a langrangian model. Indeed, in this case, age can be given by (see Parrenin et al., CP, 2007): A=int\_0^z frac{dz'} {a eta(z')} So with respect to methods like Lemieux-Dudon et al. (QSR, 2010) or Fudge et al. (CP, 2014), the method really shows its power when there is a basal melting (and therefore there is no explicit solution for A).

We agree that the model will show its full potential when more complicated ice flow models are considered, but we want to introduce the method to the ice-core community and its use together with the observed profiles measure with the new phase sensitive radar. Also we wanted to show how it deals with observations and the propagation of uncertainty to the resulting paleo-accumulation and full chronology. The main difference between our method and those described in Parrenin et al 2007, Lemieux-Dudon et al 2010 or Fudge et al 2014 ; is that we are solving the transient evolution of age-depth (\partial A/\partial t is not null), and the age-depth PDE can't be solved by integration, we believe that term could be very important for dynamical fast divides (large snow accumulation and small ice thickness).

In the first application, it is not explained how the age observations are sampled.

Done. For the synthetic data we use perfectly sampled data. We use sampled data in the Jame Ross application.

Other minors remarks below:

- p. 3827, l. 11: remove "the" before L

Done.

- p. 3829, l. 1: replace "are" by "and"

Done.

- p. 3832, I. 7: "the recovered accumulation ONLY loses..."

Done.

- p. 3833, I. 1: I think this analytical profile first appeared in Lliboutry (1979)

- p. 3833, l. 2: add subscript "I" to eta

Done.

- p. 3834, l. 26: remove "the"

Done.

- p. 3835, l. 19: "paleo-accumulation"

Done.

- p. 3836, l. 1: "paleo-accumulation"

Done.

- p. 3836, l. 4: "largest"

Done.

- fig. 3: what is the horizontal dashed line?

It was the first guess for the accumulation. We have removed the line as it makes the figure cluttered and it doesn't add that much information.

- fig. 6, legend: "a normal distribution"

Done.

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### Inferring paleo-accumulation records from ice-core data by an adjoint-based method: Application to James Ross Island's ice core

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#### Abstract

Ice cores contain a record of snow precipitation that includes information about past atmospheric circulation and mass imbalance in the polar regions. We present a novel approach to reconstruct a climatic record, by both optimally dating an ice-core and deriving from it a de-

- tailed accumulation history, that uses an adjoint-based method. The motivation of our work is the recent application of phase sensitive radar which measures the vertical velocity of an ice column. The velocity is dependent on the history of subsequent snow accumulation, compaction and compression; and in our inverse formulation of this problem, measured vertical velocity profiles can be utilized directly thereby reducing the uncertainty introduced by ice flow mod-
- elling. We first apply our method to synthetic data in order to study its capability and the effect of noise and gaps in the age-depth observations. The method is then applied to the ice core retrieved from James Ross Island, Antarctica. We show that the method is robust and that the results depend on quality of the age-depth observations and the derived flow regime around the core site. The method facilitates the incorporation of increasing detail provided by ice-core analysis together with observed full-depth velocity in order to construct a complete climatic record of the polar regions.

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#### 1 Introduction

A layer of snow deposited at some position and time on the surface of an ice sheet has today a burial rate and depth that is dependent on the weight and amount of snow accumulated above it, its metamorphosis to ice and the flow of the ice sheet. When the ice core is extracted, the chemical constituents trapped in the ice contain information of the climatic conditions during the time of deposition.

Dating the ice-core is paramount in order to interpret the climatic record. Different methods are used to establish the ice-core timeline, mainly: annual layer counting, localization of dated volcanic eruptions in the record, comparison of chemical species with other ice-cores, and ice flow modelling. Commonly, the ice-core chronology is obtained by a combination of methods

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(e.g., Hammer et al., 1978; Parrenin et al., 2007a; Lemieux-Dudon et al., 2010). Annual layer counting and the localization of known volcanic events offer accurate dating, but their use is restricted to the top of the ice-core or to sparse sections of the record.

Ice-core dating relies on ice-flow models in sections where direct chronological information is unavailable or incomplete. The assumption made is that the record of snow accumulation is 5 related to past cloud temperatures that, in turn, are derived from ice core isotope analysis (e.g., Watanabe et al., 2003; Parrenin et al., 2007b). However, this assumption can not be used on coastal areas of Antarctica or Greenland (Bromwich and Robasky, 1993; Kapsner et al., 1995) where the main driver of change in accumulation is atmospheric circulation and not the thermodynamic equilibrium of the atmosphere. However, recent advances in ice core data analysis 10 provide detailed chronologies for ice cores located in coastal areas using layer counting (e.g., Rasmussen et al., 2006; van Ommen and Morgan, 2010) or transferring timelines from reference ice-cores using stratigraphic links (e.g., Ruth et al., 2007; Lemieux-Dudon et al., 2010). The aim of this paper is to use a detailed chronology such as those, derived independently of temperature reconstructions, in order to obtain a record of paleo-accumulation. 15

Previous work has estimated paleo-accumulation and unknown ice-flow properties in order to extend the age-depth record beyond the confines of layer counting or stratigraphic links. Typ-ically, an inverse method based on direct search is applied (e.g., Dansgaard and Johnsen, 1969) or, more recently, on Monte-Carlo techniques (e.g., Parrenin et al., 2001; EPICA community members Previous work has estimated paleo-accumulation and unknown ice-flow properties in order 2004; Parrenin et al., 2007b). Here, our approach is to apply an adjoint-based method for constrained optimization, commonly employed in computational fluid dynamics (CFD) for inverse problems that are governed by partial differential equations (e.g., Petra and Stadler, 2011).

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The motivation of our work is the increasing interest in climatic records extracted from highresolution ice cores located in coastal areas of Antarctica and Greenland (e.g., van Ommen and Morgar 2010; Mulvaney et al., 2012). We have taken advantage of the recent development of a phase cussion Paper

25 sensitivity radar, that allow the direct measurement of the present vertical velocity full-depth along the ice-core (Corr et al., 2002; Jenkins et al., 2006), this greatly reduces the uncertainty introduced by ice-flow modelling (Kingslake et al., 2014). In addition, recent advances in multiice-core multi-component analysis has improved the detail in ice core chronology (e.g., Rasmussen et a 2006; Ruth et al., 2007; Lemieux-Dudon et al., 2010).

We first describe the method in Section 2 and its application to synthetic and existing data from James Ross Island ice core data (Mulvaney et al., 2012, 2014) in Section 3. At the time of writing this manuscript we do not have a suitable location where both velocity derived from phase sensitive radar and a detailed ice core timeline is available. For simplicity, we have assumed that the flow of ice follows a (Dansgaard and Johnsen, 1969) analytical approximation for the synthetic data (Sec. 3.1) and a shallow ice approximation (e.g., Hutter, 1983) combined with the measured compaction for the James Ross Island ice core case (Sec. 3.2).

#### 10 2 Methodology

#### 2.1 Description of the problem: Forward model.

The combined result of snow accumulation, compaction and compression is that a particle of ice deposited in the surface of a summit of ice-thickness H is transported with a velocity (u, v, w) within the ice. The age of a particle of ice A, represents the time elapsed for a particle of ice to get transported from the surface to a given position (x, y, z), where z represents the vertical.

The age of a particle of ice can be expressed with the pure advection equation (e.g., Hindmarsh, 2001), because the increase in the age of a particle of ice is identical to the increase in time,

$$\frac{DA}{Dt} = 1,$$

where *D* represents the material derivative. In this paper, we consider that the distribution of the age varies in time, from a given initial state  $A_0$  to the present (t = T), but we neglect the effect of horizontal advection and the local variation of thickness through time  $(\frac{\partial H}{\partial t} = 0)$ . The age of ice can then be expressed as,

 $\partial_t A + w \,\partial_z A = 1, \qquad 0 \le z \le H, \ 0 \le t \le T$   $A(z,0) = A_0, \qquad 0 \le z \le H,$   $A(H,t) = 0, \qquad 0 \le t \le T.$ (1)

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We assume that the spatial variation of the velocity only depends on rheology and not on time dependent variables such as surface accumulation or ice thickness (e.g., Parrenin et al., 2007a). This assumption is supported by the perturbation analysis of Wilchinsky and Chugunov (1997) for isothermal ice. Considering the conservation of mass, the vertical velocity is

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$$w(z,t) = -m(t) + [-a(t) + m(t)] \eta(z),$$
 (2)

where a is the surface accumulation rate, m the basal melt rate, and  $\eta$  is the shape function (sometimes referred to as thinning function). For the sake of simplicity, we refer to the surface accumulation rate and basal melt rate as accumulation and melting, as there is no possible ambiguity in this paper.

#### 15 2.2 Inverse model

The inverse problem can be formulated as finding the records of accumulation a(t) and melting m(t), and the initial distribution of age-depth  $A_0(z)$ , that minimize the difference between

observations and model results:

$$\min_{a,m,A_0} J(a,m,A_0;A) := \frac{1}{2} \int_0^H \frac{[A(z,T) - A_d]^2}{\sigma_d} P_d dz 
+ \frac{\gamma_a^R}{2} \int_0^T (\partial_t a)^2 dt + \frac{\gamma_m^R}{2} \int_0^T (\partial_t m)^2 dt 
+ \frac{\gamma_{A_0}^R}{2} \int_0^H (\partial_z A_0)^2 dz,$$
(3)

<sup>5</sup> where  $\gamma_a^R$ ,  $\gamma_m^R$  and  $\gamma_{A_0}^R$  denote the weight of the Tikhonov regularization for accumulation, melting and initial age-depth distribution.  $A_d$  is the measured age of ice,  $\sigma_d$  its estimated uncertainty and  $P_d$  is the point measurement operator for discrete data (Petra and Stadler, 2011),

$$P_d(z) = \sum_{j=1}^{N_d} \delta(z - z_j) \quad \text{for } j = 1, ..., N_d \,, \tag{4}$$

where  $N_d$  is the number of point measurements and  $\delta(z - z_j)$  is the Dirac delta function. a(t), m(t) and  $A_0(z)$  are functions of time or space that we want to find; A depends on them and it can be obtained by solving Equation 1. J is a functional that depends on a(t), m(t),  $A_0(z)$  and A(z,t).

We follow a Lagrange approach (e.g., Tröltzsch, 2010), that includes a Lagrangian multiplier function  $\lambda$  in order to find the solution of the minimization problem (Eq. 3) constrained by the Discussion Paper

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forward model (Eq. 1).

$$\mathcal{L}(a, m, A_0; A, \lambda) = J(a, m, A_0; A)$$
  
+ 
$$\int_{0}^{T} \int_{0}^{H} \lambda(\partial_t A + w \partial_z A - 1) dz dt$$
  
+ 
$$\int_{0}^{H} \lambda(z, 0) [A(z, 0) - A_0] dz$$

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The optimal solution is obtained by setting the variations (functional derivatives) of the Lagrangian  $\mathcal{L}$  with respect all variables to zero. The Lagrangian in Equation 5 verifies that setting the functional derivative of the Lagrangian with respect to the Lagrangian multiplier to zero  $(\delta_{\lambda}\mathcal{L}=0)$  is equivalent to the forward problem, also known as state equation (Eq. 1). The details of the derivation of the optimal system of equations are described in the Appendix.

Setting the variations of  $\mathcal{L}$  with respect to the age ( $\delta_A \mathcal{L} = 0$ ) leads to the adjoint problem for  $\lambda$ , that in the strong form can be written as,

$\partial_t \lambda + \partial_z (w  \lambda) = 0,$	$0 \leq z \leq H, \ 0 \leq t \leq T$	
$\lambda(z,T) = \frac{A_d - A}{\sigma_d} P_d,$	$0 \le z \le H,$	
$\lambda(0,t) = 0,$	$0 \le t \le T.$	(6)

Finally, the so-called control equations, are obtained by calculating the variations of  $\mathcal{L}$  with respect to accumulation, melting and initial distributions of age and setting them to zero ( $g_a =$ 

(7)

(8)

$$\delta_{a}\mathcal{L} = 0, g_{m} = \delta_{m}\mathcal{L} = 0 \text{ and } g_{A} = \delta_{A_{0}}\mathcal{L} = 0):$$

$$g_{a} = -\int_{0}^{H} \eta \left(\lambda \partial_{z}A\right) dz - \gamma_{a}^{R} \partial_{t}^{2} a = 0,$$

$$g_{m} = \int_{0}^{H} (\eta - 1)(\lambda \partial_{z}A) dz - \gamma_{m}^{R} \partial_{t}^{2} m = 0,$$

$$g_{A} = -\lambda(z, 0) - \gamma_{A}^{R} \partial_{z}^{2} A_{0} = 0.$$

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#### 2.3 Numerical Solution

The system of Equations composed by the state equation (Eq. 1), the adjoint equation (Eq. 6) and the gradients (Eq. 7) represent a complex non-linear system of equations. In order to solve the system, we use a steepest decent method (e.g., Petra and Stadler, 2011).

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First we assume initial solutions for accumulation, melting and initial distribution of age  $(a^k, m^k \text{ and } A_0^k)$ . We then solve the state equation (Eq. 1), and using the inferred solution of age  $A^k$ , we solve the adjoint equation backward in time to obtain the solution of the Lagrange multiplier  $\lambda^k$ .

In order to update the solution for accumulation, melting and initial distributions of age and temperature, we increase them in the direction of steepest descent of the Lagrangian.

$$egin{array}{rcl} a^{k+1} &=& a^k+eta_a g_a, \ m^{k+1} &=& m^k+eta_m g_m, \ A_0^{k+1} &=& A_0^k+eta_A g_A, \end{array}$$

#### where $\beta_a$ , $\beta_m$ are $\beta_A$ are parameters.

The values of  $\beta_a$ ,  $\beta_m$  and  $\beta_A$  are calculated each iteration using a backtracking line search algorithm (e.g., Dennis and Schnabel, 1996, §6.3.2). The method assumes sufficiently large ini-

tial values for  $\beta_a$ ,  $\beta_m$  and  $\beta_A$ , that are successively halved until the corresponding decrease in the objective function J (Eq. 3) fulfil the Armijo (1966) condition,

$$J(x^{k}) - J(x^{k+1}) \ge -c\,\beta_x \,g_x^2\,, \tag{9}$$

where x represents the state variables a, m or  $A_0$ ;  $g_x$  the respective gradients of the objective function  $g_a$ ,  $g_m$  or  $g_A$ ;  $\beta_x$  the parameters  $\beta_a$ ,  $\beta_m$  or  $\beta_A$ ; and the constant c is fixed to  $c = 10^{-2}$ .

The values of  $\gamma_a^R$ ,  $\gamma_m^R$  and  $\gamma_{A_0}^R$ , are chosen by inspection of the L-curve (e.g., Hansen, 2000). The L-curve is a plot of the norm of the regularization term  $(\int_0^T (\partial_t a)^2 dt, \int_0^T (\partial_t m)^2 dt)$ or  $\int_0^H (\partial_z A_0)^2 dz$ ) versus the difference in age-depth between observation and model results  $\left(\int_{0}^{H} P_{d} [A(z,T) - A_{d}]^{2} / \sigma_{d} dz\right)$  for different values of the regularization parameter. The Lcurve has two distinctive sections: for sufficiently small values of the regularization param-10 eter, the differences between data and model dominate the objective function, and a gradual increase in the smoothing of the solution implies a gradual increase in the differences between data and model; conversely, for sufficiently large values of the regularization parameter, the

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of the solution translates into sharper differences between data and model. The curve typically is L-shaped, and hence its name. The regularization parameters are chosen so that their corresponding terms in the objective function sit on the L-curve between these two sections, that is, the corner of the L.

regularization term dominates the objective function, and a gradual increase in the smoothing

Regarding the numerical techniques, we solve the state equation (Eq. 1) and the adjoint equation (Eq. 6), by using a operator combined Semi-Lagrangian Crank-Nicholson algorithm 20 (SLCN) (Spiegelman and Katz, 2006) in a equispaced grid of elevation  $\{z_i\}$ .

The second order two-level Semi-Lagrangian scheme (e.g., Staniforth and Côté, 1991) solves the advection terms as an ordinary differential equation along the trajectory that connects from some take-off elevation  $z_*$  at time  $t = (n)\Delta t$  to a regular grid point  $z_i$  at time  $t = (n+1)\Delta t$  in the state equation, that is solved forward in time, and at time  $t = (n-1)\Delta t$  in the adjoint equa-

25 tion, that is solved backward in time  $(\Delta t \rightarrow -\Delta t, w \rightarrow -w)$ . The Crank-Nicolson algorithm is used to discretize the diffusive terms with a central difference.

The discretized state equation (Eq. 1) and the adjoint equation (Eq. 6), using the SLCN method are respectively,

$$A_i^{n+1} = 1 + A_*, (10)$$

$$(1 - \frac{\Delta t}{2} \delta w_i) \lambda_i^{n-1} = (1 + \frac{\Delta t}{2} \delta w_i) \lambda_*; \qquad (11)$$

<sup>5</sup> where  $\delta$  denotes the gradient discrete operator

$$(\nabla f)|_{z_i} \approx \delta f_i = \frac{f_{i+1} - f_{i-1}}{2\Delta z},$$

and ()<sub>\*</sub> denotes the value at the take-off position  $z_*$  and time  $t = (n)\Delta t$ .

#### **3** Results

#### 3.1 Recovering accumulation from synthetic age-depth observations

<sup>10</sup> In order to study the capability of our method to recover paleo-accumulation from age-depth observations, we have generated synthetic observations by adding random noise to a reference solution.

The reference accumulation solution varies over 10 kyr as,

$$a(t) = [0.2 + 0.1\sin(2\pi t/\tau_1) + 0.05\sin(2\pi t/\tau_2)] \text{ m yr}^{-1},$$

where  $\tau_1 = 10$  kyr, and  $\tau_2 = 1$  kyr. Figure 1 shows the reference accumulation and age-depth. In this Section, we assume that there is no melting, and that the shape function (Eq. 2) follows Dansgaard and Johnsen (1969),

$$\eta(z) = \begin{cases} \frac{z - z_k/2}{H - z_k/2} & z_k \le z \le H \\ \frac{z^2/2}{z_k(H - z_k/2)} & 0 \le z \le z_k \end{cases},$$
(12)

where  $z_k$  is a parameter that we fix to  $z_k = 0.3 H$ . In addition, we assume that the initial age distribution (A(t=0)) is exact and that it is a steady-state solution of the velocity distribution at time t = 0.

We first check our model by applying it to the age-depth derived from the reference accumu-<sup>5</sup> lation. The algorithm (Sec. 2.3) converges in 100-200 iterations, depending on the initial guess and the stopping criteria. After several numerical tests we used a grid with a meter of vertical resolution and 50 yr time-steps. In this simulation we assume perfectly sampled data, i.e. the age-depth distribution is available at the numerical grid points. The results are not reported here as the recovered accumulation and age-depth converges to the exact reference accumulation.

<sup>10</sup> Then, we add a 1% random noise to the reference age-depth solution and apply our method to recover accumulation and age-depth. That is, we add to each sample of the reference age-depth value  $A_i$  an independent value sampled uniformly in the interval  $[-0.01A_i, 0.01A_i]$ . The results are in Figure 1. The recovered age-depth is nearly identical to the reference age-depth (under 0.1% difference), even in the deepest area of the record. On the other hand, the random noise introduce differences between recovered and reference accumulation: The difference increase with time from the present up to a value of about 10%.

Next, we investigate the effect of increasing noise. We compare the recovered accumulation from synthetic data obtained adding 1%, 5% and 10% random noise to the reference age-depth. The results are shown in Figure 2. The solution deteriorates when random noise increases, but the recovered accumulation only loses information for small wavelengths.

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In the final numerical experiment (Fig. 3), we study the effect of not having data in an area. In the simulation we assumed that there is no data in 400m < z < 600m and that there is a 1% random noise in the synthetic age-depth. We find that the effect of not having any data over a given depth range of the bore hole on the inversion, is a period of time (area highlighted in Fig.

<sup>25</sup> 3) over which the retrieved accumulation is mainly constrained by the initially assumed profile and the regularization applied.

#### 3.2 Recovering paleo-accumulation from James Ross Island ice core

In this Section, we apply the method to the ice core extracted from James Ross Island, a large island off the south-east side and near the north-eastern extremity of the Antarctic Peninsula. The data used in this section and its climatological implications are discussed in Mulvaney et al. (2012) and Mulvaney et al. (2014).

Figure 4 shows the timeline for the James Ross Island ice core that is provided by fixed markers derived from local and global volcanic events with unequal estimated uncertainty (details in Mulvaney et al. (2012), Supplementary Table 1).

We assume that the shape function (Eq. 2) can be expressed as,

$$\eta = \frac{\rho_I}{\rho} \eta_I$$

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where  $\rho$  is the measured density at a given depth,  $\rho_I = 910 \text{ kg m}^{-3}$  is the reference density of ice, and  $\eta_I$  is the shape function for ice. We further assume that  $\eta_I$  follows a shallow ice approximation(e.g., Hutter, 1983),

$$\eta_I(s) = 1 - s \left( \frac{n+2}{n+1} - \frac{s^{n+1}}{n+1} \right) ,$$

where s is the normalized depth (s = (H - z)/H). In order to measure the sensitivity to the uncertainty in ice-flow in the recovered age-depth distribution and accumulation record, we assume that the rheological index n varies in the range  $2 \le n \le 5$ .

We assume that there is no melting at the base of the dome as a temperature of -8.5C was recorded at the bottom of the ice-core. Also, because the time interval we are interested in is only 3 kyr, we avoid the problem of guessing  $A_0$  by expanding the simulation time until 10 kyr before present. That way, our solution is not sensitive to the value of  $A_0$ . Based on different numerical test we use a grid with 0.3 m resolution and 10 yr time-step.

The recovered age-depth (Fig. 4) follows the intervals of the observed measurements, and the uncertainty introduced by the ice-flow parameter n is smaller than a 1%, indiscernible in the

figure. On the other side, the recovered paleo-accumulation (Fig. 5) follows roughly the stable water isotope ( $\delta D$ ), that is a proxy for temperature, but the result is not clear due to the small number of age markers (12 markers in 3 kyr) and the uncertainty introduced by the ice-flow parameter n. The uncertainty increases with time from the present and it becomes about 20% of the estimated value after 3 kyr.

Finally, to estimate the sensitivity of the method to age-depth uncertainty, we use a basic Monte Carlo method (e.g., Campolongo et al., 2000). The error propagation is obtained by calculating the standard deviation, at a given depth, from a set of one hundred results for both accumulation and age-depth. For each one of the one hundred simulations, we resample the measured age-depth observations assuming a normal distribution with standard deviation equal to one third of the uncertainty estimation (so that 99% of the samples lie within the range of observations).

The results are shown in Figure 6. The estimation of uncertainty in observed age-depth is variable from 1% at certain depths to about 10% in the deepest sections of the ice core. Similarly to the uncertainty propagation introduced by the ice-flow (included in the Figure), uncertainty in accumulation increases with time from the present but reaching a maximum of about 15% after 3000 years.

#### 4 Discussion

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The quality of the information recovered from an inverse problem is always related to the quality of the observed measurements and to the nature of the assumptions made in the forward model. In this paper, we have analysed the effect on paleo-accumulation (recovered information) of random noise, gaps and uncertainty in the age-depth distribution (observed measurements). We also evaluate the propagation of uncertainty introduced by assumptions in the forward model, that follows the compaction and compression of ice with time (Fig. 5). That uncertainty in ice-flow is simplified in this study as the uncertainty in the rheological index n.

The experiments with synthetic data (Sec. 3.1) show that our method is robust: In perfectly sampled data (Fig. 2), it recovers the reference accumulation in the presence of random noise,

and, even when the increase in noise deteriorates the accumulation, it recovers time-averaged values as the details are first lost in the high temporal frequencies. Besides, when there are gaps in the data (Fig. 3), the retrieved profile is constrained by the regularization. We find that the smoothing in the accumulation transforms, after solving the forward model, into a smooth age-depth (Fig. 3). In contrast, a typical polynomial interpolation of the age-depth leads to spurious accumulation records due to the non-linearity introduced by the Age equation (Eq. 1) (Fudge et al., 2014).

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The sensitivity analysis to the James Ross ice core data (Fig. 6), shows that between 1% and 10% of uncertainty in the observations results in similar uncertainty in paleo-accumulation. On the other hand, the propagation of uncertainty from the unknown parameter in ice flow model has a stronger effect on the accumulation (about 20%) than in the age-depth (under 1%).

It is not the objective of this study to evaluate the use of modelling in ice core dating, but this later result shows that, in our case study, there is a relatively small the sensitivity (under a 1%) of age-depth to uncertainty in ice-flow modelling. Age-depth depends on accumulation; and in the ice cores where accumulation can be extracted from temperature reconstructions and age-depth is constrained by fixed-markers, our test case supports the use of modelling in ice core dating (e.g., Parrenin et al., 2007a; Ruth et al., 2007; Lemieux-Dudon et al., 2010).

We only consider simplified ice flow shape functions (derived from Dansgaard and Johnsen (1969) in Sec. 3.1 and Shallow Ice Approximation in Sec. 3.2) as they are easier to analyze and
<sup>20</sup> because our aim is to incorporate measured full-depth vertical velocity as they become available in the future. Our main assumption is that the spatial variability of the velocity depends on compaction and rheology, and the time dependence is proportional to the combined result of accumulation and surface thinning. This assumption is partially supported by the perturbation analysis of Wilchinsky and Chugunov (1997), that assumes isothermal ice; but we do not consider the
<sup>25</sup> effect of time evolution on firnification (e.g., Arthern and Wingham, 1998), temperature along the core (e.g., Nereson and Waddington, 2002), ice fabric (e.g., Martín and Gudmundsson, 2012), dome migration (e.g., Martín et al., 2009), horizontal advection or thinning (e.g., Huybrechts et al., 2007).

More complete ice-flow models can be incorporated into the inverse problem. The method consist of adding the weak form of the system of equations for the velocity (ice-flow model) to the Lagrangian  $\mathcal{L}$  in Equation 5 (e.g., Petra and Stadler, 2011, Sec. 3). The challenge is that the data extracted from the ice-core, that is constraining the climatic reconstruction, is onedimensional but the ice-flow problem is three-dimensional with a poorly constrained rheology. The main issue, when considering horizontal advection, is that the ice along the core could have been deposited at the surface at a different position that the actual ice-core surface position, and ice-domes near the coast are areas where the gradients in surface accumulation can be high (Lenaerts et al., 2014). We expect that the analysis of full-depth velocity datasets near ice-rises (Kingslake et al., 2014) provides information on spatial variations of ice-flow on ice-domes and

10 (Kingslake et al., 2014) provides information on spatial variations of ice-flow on thelp to reconstruct the paleo-accumulation records.

#### 5 Conclusions

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The present study describes a novel application of an adjoint-based method to derive paleoaccumulation records from ice core chronology. The method is designed for ice cores in coastal areas of Antarctica and Greenland because it does not rely on temperature reconstructions.

Our approach is to follow a Lagrange method for constrained optimization, commonly employed in CFD inverse problems governed by partial differential equations. We apply our method to synthetic and existing data from the James Ross Island ice core. We show that the method is robust, as it retrieves paleo-accumulation from data with random noise and it reacts well to gaps in the late. We also also accumulation of the paleo accumulation of the paleo accumulation from data with random noise and it reacts well to gaps

<sup>20</sup> in the data. We also show that the quality of the paleo-accumulation depends on the quality of the age-depth observations, uncertainty and sampling, and the uncertainty in ice-flow.

Besides, in our case study on James Ross Island ice core, where full-depth velocity measurements are not available, the largest uncertainty in the inferred paleo-accumulation is a consequence of the unknown ice-flow parameters. It increases with time until a maximum of about 20%. In addition, an uncertainty in the chronology between 1% and 10% propagates into a similar uncertainty in paleo-accumulation.

Our ambition is to incorporate to the method full-depth vertical velocity obtained with phase sensitive radar, in order to reduce the uncertainty introduced by ice-flow modelling, and a detailed chronology, provided by ice core analysis, in order to obtain a optimized chronology and a detailed paleo-accumulation record.

#### 5 Appendix A: Derivation of the model system of equations

The Lagrangian  $\mathcal{L}$  (Eq. 5) has been defined so that its minimization is equivalent to the minimization of J (Eq. 3), the difference between observations and model results, and the forward model (Eq. 1). In this Section, we calculate the functional derivative of  $\mathcal{L}$  with respect to the Lagrangian multiplier  $\lambda$ , to check that the minimization of  $\mathcal{L}$  is constrained to verify the forward model (Eq. 1); with respect to the age, to obtain the adjoint problem (Eq. 6); and with respect to the control variable a, to calculate its gradient  $g_a$  (Eq. 7). The gradients for melting ( $g_m$ ) and initial age distribution ( $g_A$ ) in Equation 7 can be obtained in a similar way.

By definition, the functional derivative of  $\mathcal{L}$  with respect to the Lagrange multiplier  $\lambda$  in a direction  $\overline{\lambda}$  is,

<sup>15</sup> 
$$\delta_{\lambda} \mathcal{L}(a, m, A_0; A, \lambda)(\bar{\lambda}) = \left[\frac{d}{d\epsilon} \mathcal{L}(a, m, A_0; A, \lambda + \epsilon \bar{\lambda})\right]_{\epsilon=0}$$

where  $\epsilon$  is a constant and  $\overline{\lambda}$  is an arbitrary function.

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The result of setting to zero the functional derivative of  $\mathcal{L}$  with respect to the Lagrange multiplier is,

$$\delta_{\lambda}\mathcal{L}(a,m,A_0;A,\lambda)(\bar{\lambda}) = \int_0^T \int_0^H \bar{\lambda}(\partial_t A + w \,\partial_z A - 1) \,dz \,dt + \int_0^H \bar{\lambda}(z,0) \left[A(z,0) - A_0\right] \,dz = 0,$$

which is the weak form of the forward model (Eq. 1). That is, because  $\overline{\lambda}$  is an arbitrary function, the Equation is true when the age distribution verifies the forward model.

Similarly, by setting to zero the functional derivative of  $\mathcal{L}$  with respect to the Age, we obtain:

$$\delta_A \mathcal{L}(a, m, A_0; A, \lambda)(\bar{A}) = \int_0^H \bar{A} \frac{[A(z, T) - A_d]}{\sigma_d} P_d dz$$
$$+ \int_0^T \int_0^H \lambda(\partial_t \bar{A} + w \, \partial_z \bar{A}) \, dz \, dt + \int_0^H \lambda(z, 0) \bar{A}(z, 0) \, dz = 0.$$

We then integrate by parts  $\lambda \partial_t \bar{A}$  with respect to time and  $\lambda w \partial_z \bar{A}$  with respect to z,

$$\int_{0}^{H} \bar{A} \frac{[A(z,T) - A_d]}{\sigma_d} P_d dz - \int_{0}^{T} \int_{0}^{H} \bar{A} [\partial_t \lambda + \partial_z (w\lambda)] dz dt$$

$$+ \int_{0}^{H} [\lambda(z,T)\bar{A}(z,T) - \lambda(z,0)\bar{A}(z,0)] dz$$

$$+ \int_{0}^{T} [\lambda(H,t)w(H)\bar{A}(H,t) - \lambda(0,t)w(0)\bar{A}(0,t)] dt$$

$$+ \int_{0}^{H} \lambda(z,0)\bar{A}(z,0) dz = 0.$$

After setting  $\bar{A}(H,t)$  to zero, as it has to have the same properties that the age-depth distribution that is null at the surface, we obtain,

$$\int_{0}^{H} \bar{A} \left[ \lambda + \frac{\left[ A(z,T) - A_d \right]}{\sigma_d} P_d \right] dz - \int_{0}^{T} \int_{0}^{H} \bar{A} \left[ \partial_t \lambda + \partial_z(w\lambda) \right] dz \, dt - \int_{0}^{T} \bar{A}(0,t)\lambda(0,t)w(0) dt = 0,$$

that is the weak form of the Adjoint problem (Eq. 6).

Discussion Paper

Discussion Paper

Finally, we calculate the gradient of  $\mathcal{L}$  with respect to the accumulation as,

$$\delta_a \mathcal{L}(a, m, A_0; A, \lambda)(\bar{a}) = \gamma_a^R \int_0^T [\partial_t a \partial_t \bar{a}] dt + \int_0^T \int_0^H \lambda \bar{a} \eta \partial_z A dz dt ,$$

that, applying integration by parts to the first term of the right-hand side, can be written as,

$$\delta_a \mathcal{L}(a, m, A_0; A, \lambda)(\bar{a}) = \gamma_a^R \int_0^T \bar{a} \left[ -\partial_t^2 a \int_0^H \lambda \bar{a} \eta \partial_z A dz \right] dt + \bar{a}(T) \partial_t a(T) - \bar{a}(0) \partial_t a(0) = 0,$$

5 that is the weak form of the gradient defined in Equation 7.

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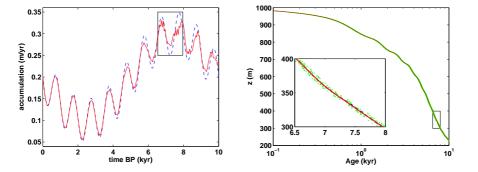
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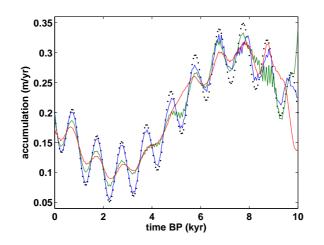
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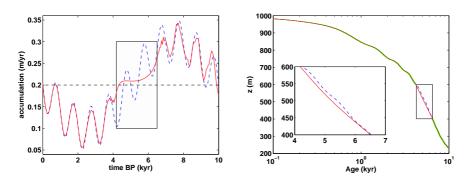
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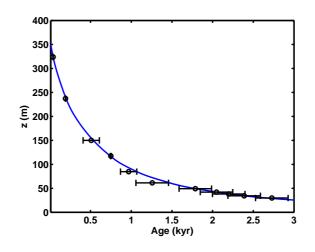
**Figure 1.** Recovered accumulation (red, left panel) and age-depth distribution (red, right panel) from age-depth synthetic data (green, right panel). The synthetic age-depth distribution has been obtained by adding 1% uniform noise to the reference solution (blue right-panel) derived from the reference accumulation record (blue, left panel). Inset in the right panel zooms into the age-depth profile in an area that is highlighted both in the accumulation record and in the age-depth distribution.



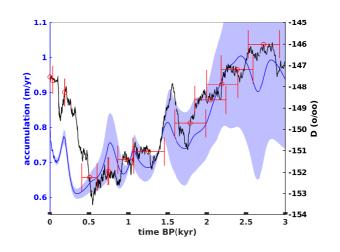
**Figure 2.** Recovered Accumulation from the synthetic age-depth distribution obtained adding 1% (blue), 5% (green) and 10% (red) uniform noise to the solution derived from the reference accumulation (dotted line).



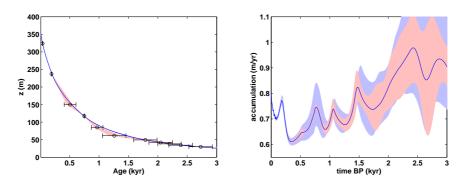
**Figure 3.** Recovered accumulation (red, left panel) and age-depth distribution (red, right panel) from age-depth synthetic data (green, right panel). The synthetic age-depth distribution has been obtained by adding 1% uniform noise to the reference solution (blue right-panel) derived from the reference accumulation record (blue, left panel), and considering a gap in the data (400m < z < 600m). Inset in the right panel zooms into the age-depth results where there is a gap in the age-depth data.



**Figure 4.** Recovered age-depth (blue) and observed age-depth (black) from (Mulvaney et al., 2012). The uncertainty in recovered accumulation due to unknown ice-flow parameter n ( $2 \le n \le 5$ ) is indiscernible in the plot.



**Figure 5.** Recovered accumulation (blue) from James Ross ice core observed age-depth and stable water isotope  $\delta D$  (black). Red symbols represent the uncertainty in age-depth at the points where absolute markers where found (Mulvaney et al., 2012). The area in blue represents uncertainty in recovered accumulation due to unknown ice-flow parameter n ( $2 \le n \le 5$ ). The stable water isotope  $\delta D$  has not been used for the inversion and is plotted only for reference.



**Figure 6.** Sensitivity analysis to uncertainty in chronology (red) and shape function  $\eta$  (blue). The uncertainty in chronology is assumed to follow a normal distribution. The uncertainty in the shape function  $\eta$  is represented by the range  $2 \le n \le 5$  for the rheological index in the Glen flow law.